

# Software Update on Embedded Systems



Do not brick your device

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# Introduction



- Me:
  - Software Engineer at DENX, Gmbh
  - U-Boot Custodian for Freescale's i.MX
  - Focus on Linux embedded with PowerPC and ARM processors.

# Agenda



- Why upgrade ?
- Why is it different with a Linux-PC ?
- Upgrading strategies
- Swupdate

# Why do we need to update an embedded system ?



- It is not only hardware
- Bug fixes
- New features can be added
- Security issues : heartbleed, bad implementation...

The screenshot shows a web interface for 'Propsteikirche St. Stephanus'. On the left, there is a vertical menu with buttons for 'Info', 'Programm 1', 'Programm 2', 'Sonderprogr.', and 'Stundenschlag'. The 'Stundenschlag' button is highlighted in green. The main content area is titled 'Glockenparameter' and contains a table with the following data:

Glocke	Erstschlag	Durchlisten	Auslisten	Ausklängen
1	24.0 Sek	65.0 Sek	60.0 Sek	3.0 Sek
2	11.0 Sek	28.0 Sek	180.0 Sek	40.0 Sek
3	16.0 Sek	36.0 Sek	135.0 Sek	35.0 Sek

# Why is ES different ?



- Power failure
- Bad firmware
- Communication errors in case of remote update
- No access to target

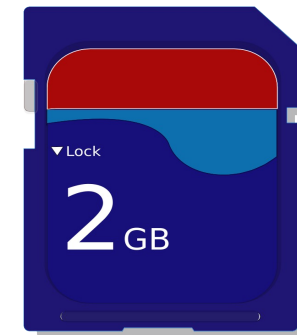
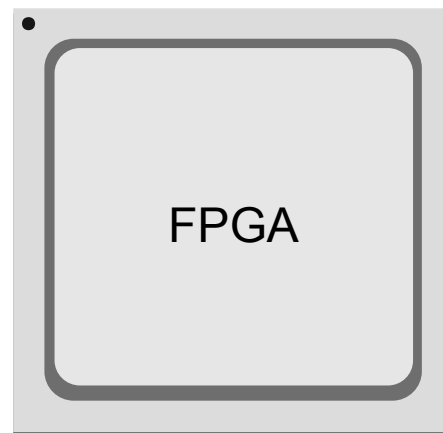
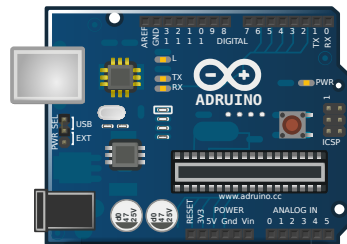
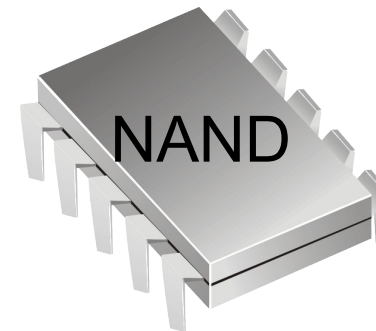
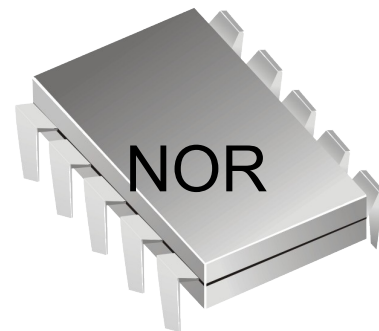
Target must recover from errors !

# Which elements must be updated ?



- Bootloader (dangerous !)
- Kernel + DT
- Root filesystem
- Application data, other filesystems..
- Customer data (migration )
- Specific software (FPGA bitstream,...)

# Where is a new SW installed ?



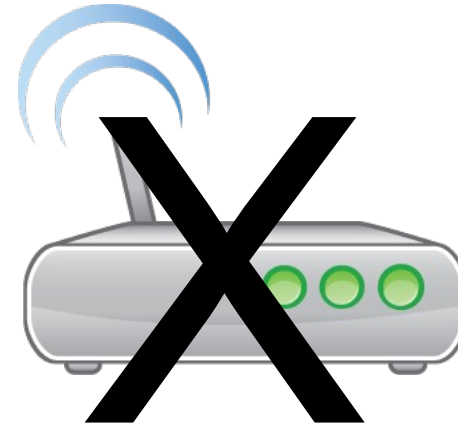
# Which interface ?



- Local:
  - Local storage (USB, SD,..)
  - Local peripheral (USB as device, UART,..)
- Remote:
  - HTTP / web based
  - FTP
  - Proprietary protocol
  - Many more...

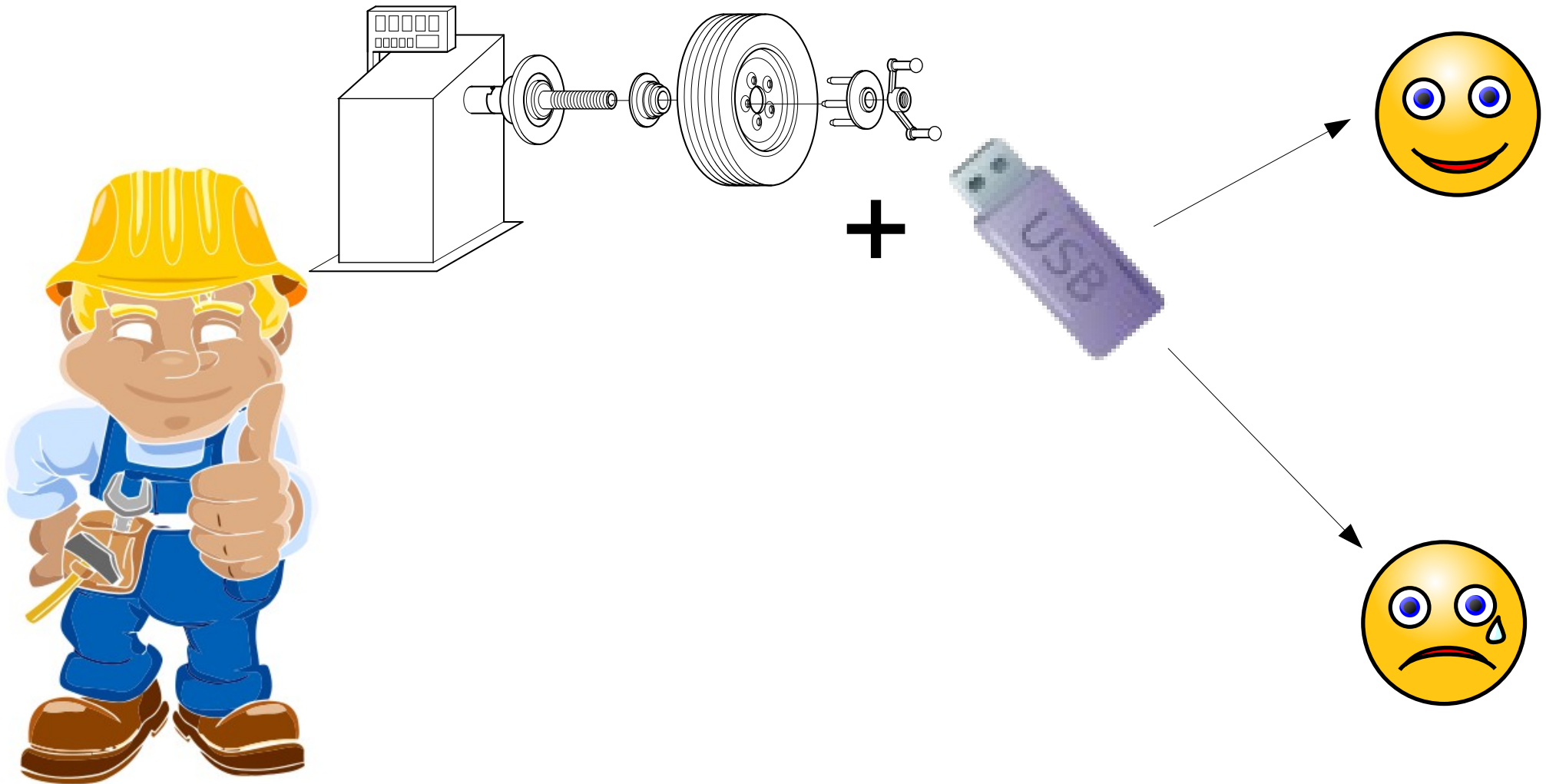


# Who will update ?



# No expertise required

denix  
software  
engineering



# System upgrade solutions



- Bootloader upgrade
- Linux upgrade
  - Package Manager
  - Rescue image or specific application
  - From the running application

# Bootloader



- ✘ Limited access to peripherals (drivers, filesystems)
- ✘ Implementation in bootloader not in sync with Linux
- ✘ Limited network support (UDP, not TCP)
- ✘ Limited UI with an operator
  
- ✓ Update is simpler
- ✓ Smaller footprint

# Linux App



## ✘ Footprint

- ✓ Availability of all drivers used by the product
- ✓ A lot of tools/libraries

# package manager as distro ?



- ✘ Upgrade is not atomic
  - ✘ Nightmare for test engineers/support
  - ✘ New firmware partially written
  - ✘ More places where things can go wrong
- 
- ✔ Small update image

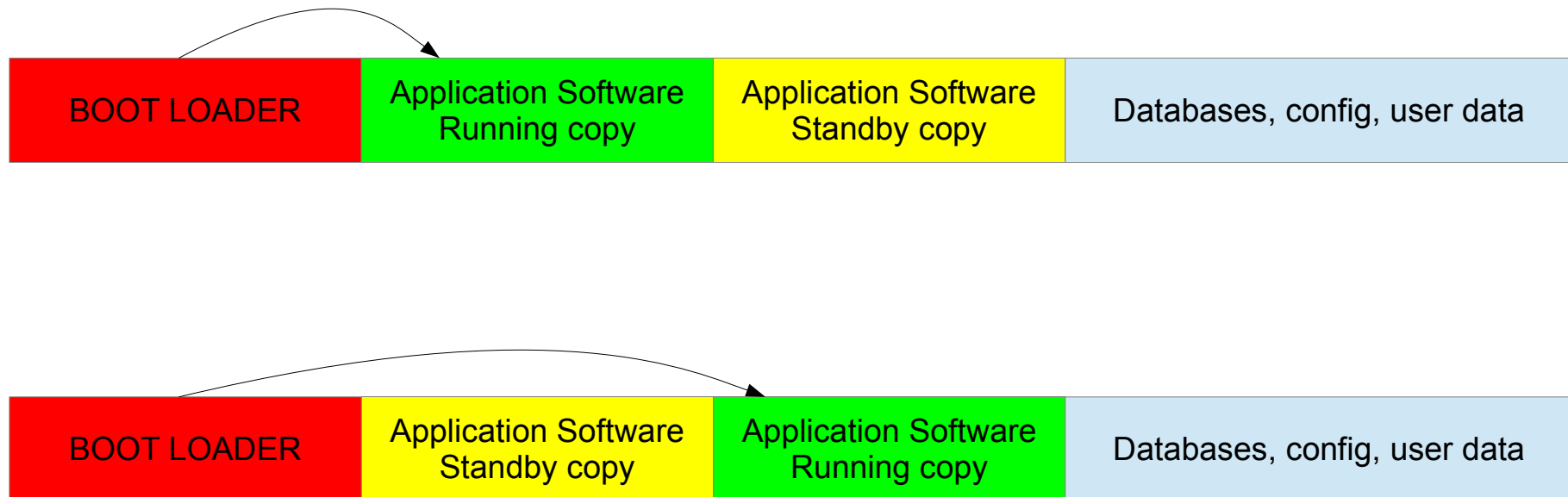


# Full update



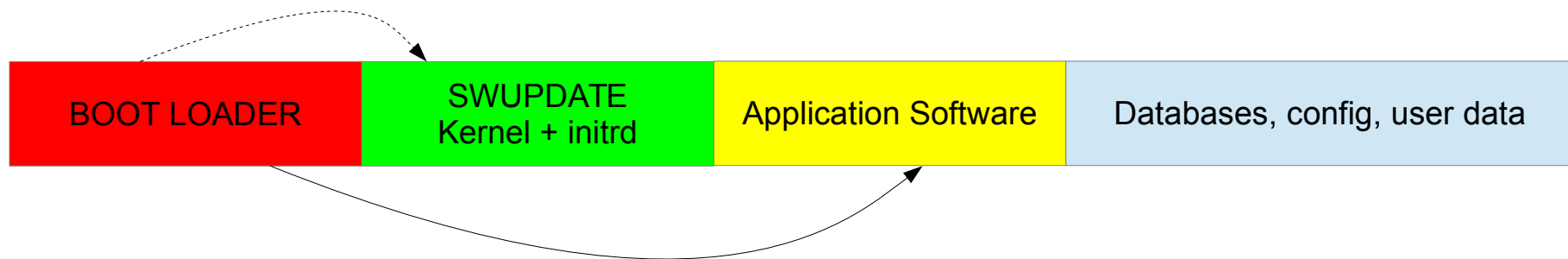
- ✘ Size, Time to transfer
- ✔ Atomic: it works or not
- ✔ Single image delivery

# Double copy strategy





# Single copy (rescue)



# swupdate: FLOSS upgrade sw



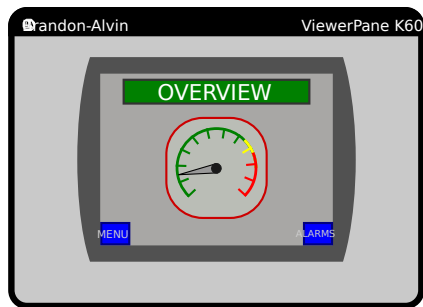
- Missing an open source upgrade software for ES
- Take care of failure mechanism
- Hardware / software compatibility
- Proof correctness images to be installed (chksum,..)
- Partitioning storage
- Local or remote install

# Swupdate-2

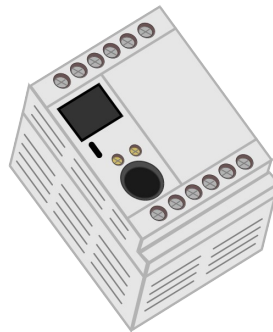


- Scriptable (Lua), pre- and postinstall scripts
- Single image for multiple devices
- Easy for users to perform update
- Missing : signed images !

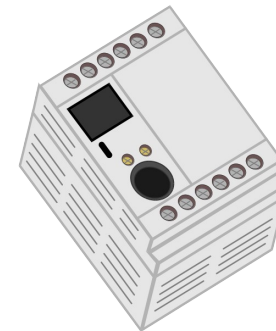
# Handling hardware differences



HMI



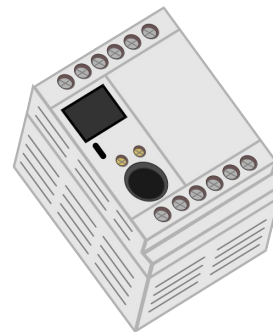
Type A-1



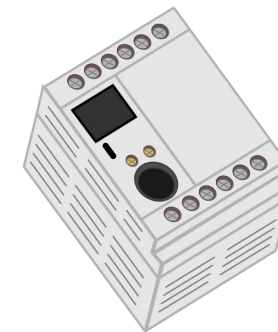
Type A-2



Gateway



Type A-3

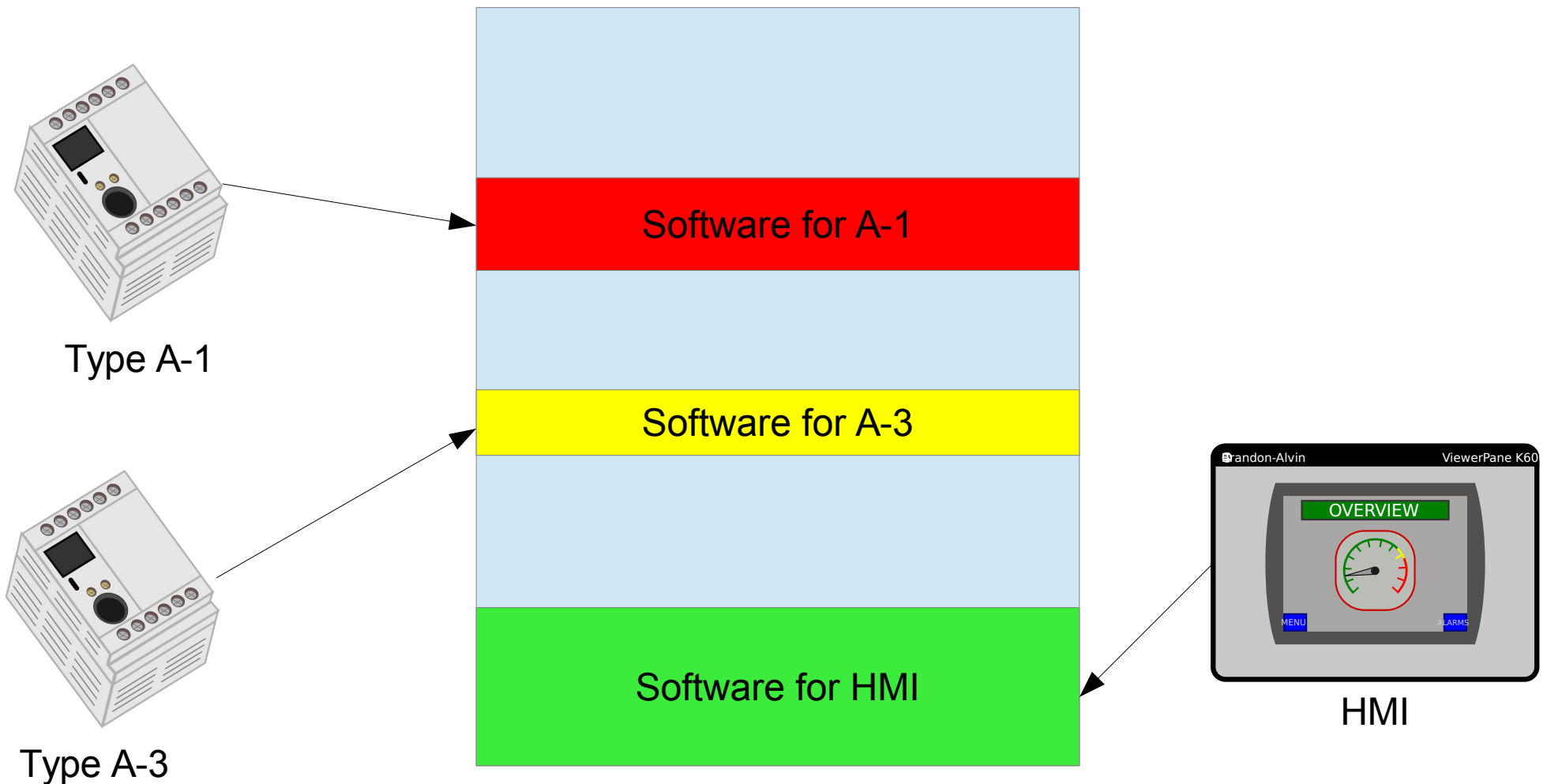


Type A-4

# One release, multiple devices



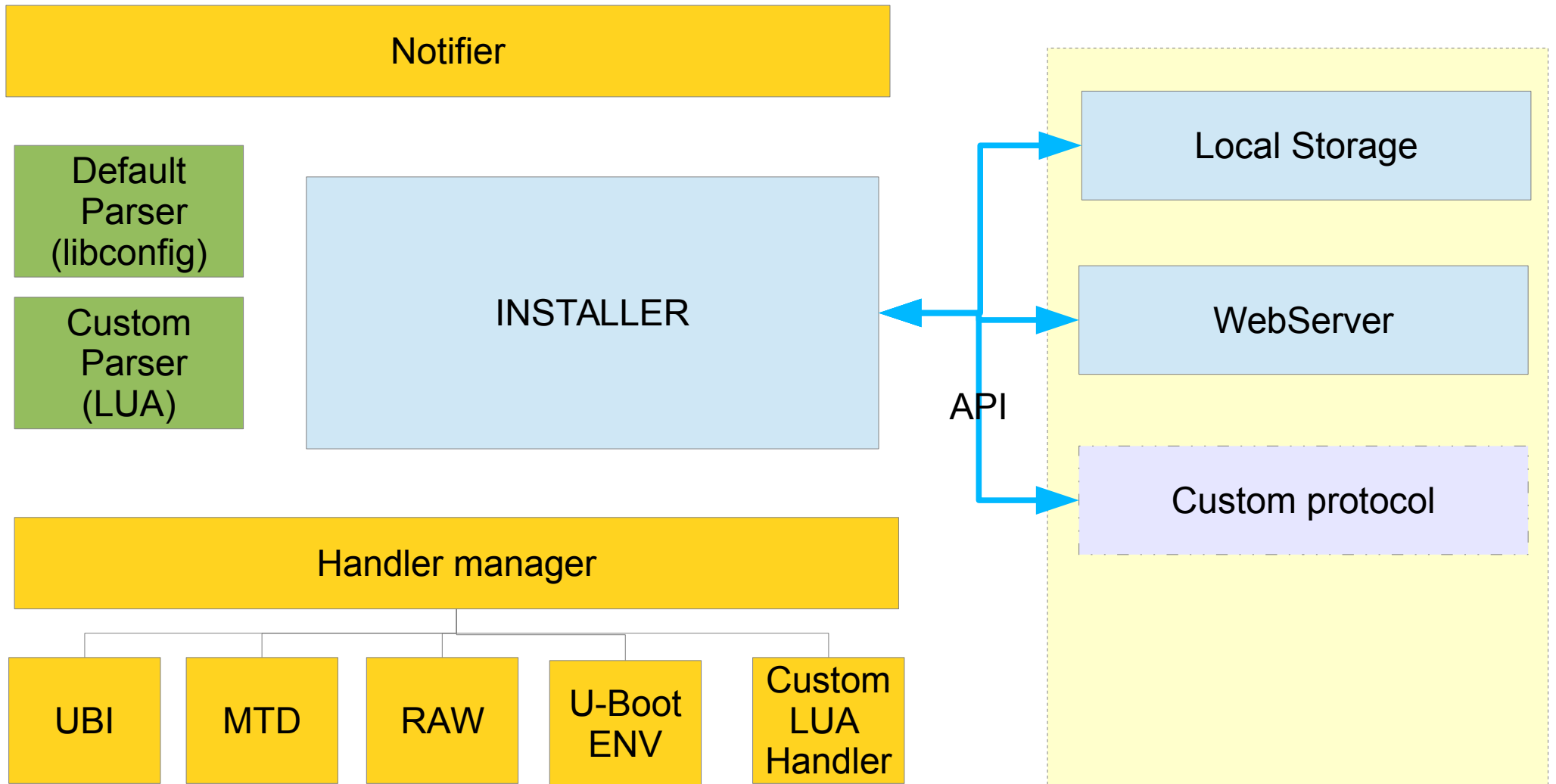
Release XX.YY for device family



# Single image structure



# Swupdate architecture



# Handling HW differences



```
software =  
{  
  version = "0.1.0";  
  
  target-1 = {  
    images: (  
      {  
        ...  
      }  
    );  
  };  
  
  target-2 = {  
    images: (  
      {  
        ...  
      }  
    );  
  };  
}
```



# sw-description



```
software =
{
    version = "0.1.0";

    myboard = {

        hardware-compatibility: [ "1.2", "1.3", "18#010071"];

        partitions: ( /* UBI Volumes */
            {
                name = "rootfs";
                device = "mtd10";
                size = 104896512; /* in bytes */
            },
            {
                name = "kernel";
                device = "mtd9";
                size = 4194304; /* in bytes */
            }
        );
    };
};
```

# sw-description



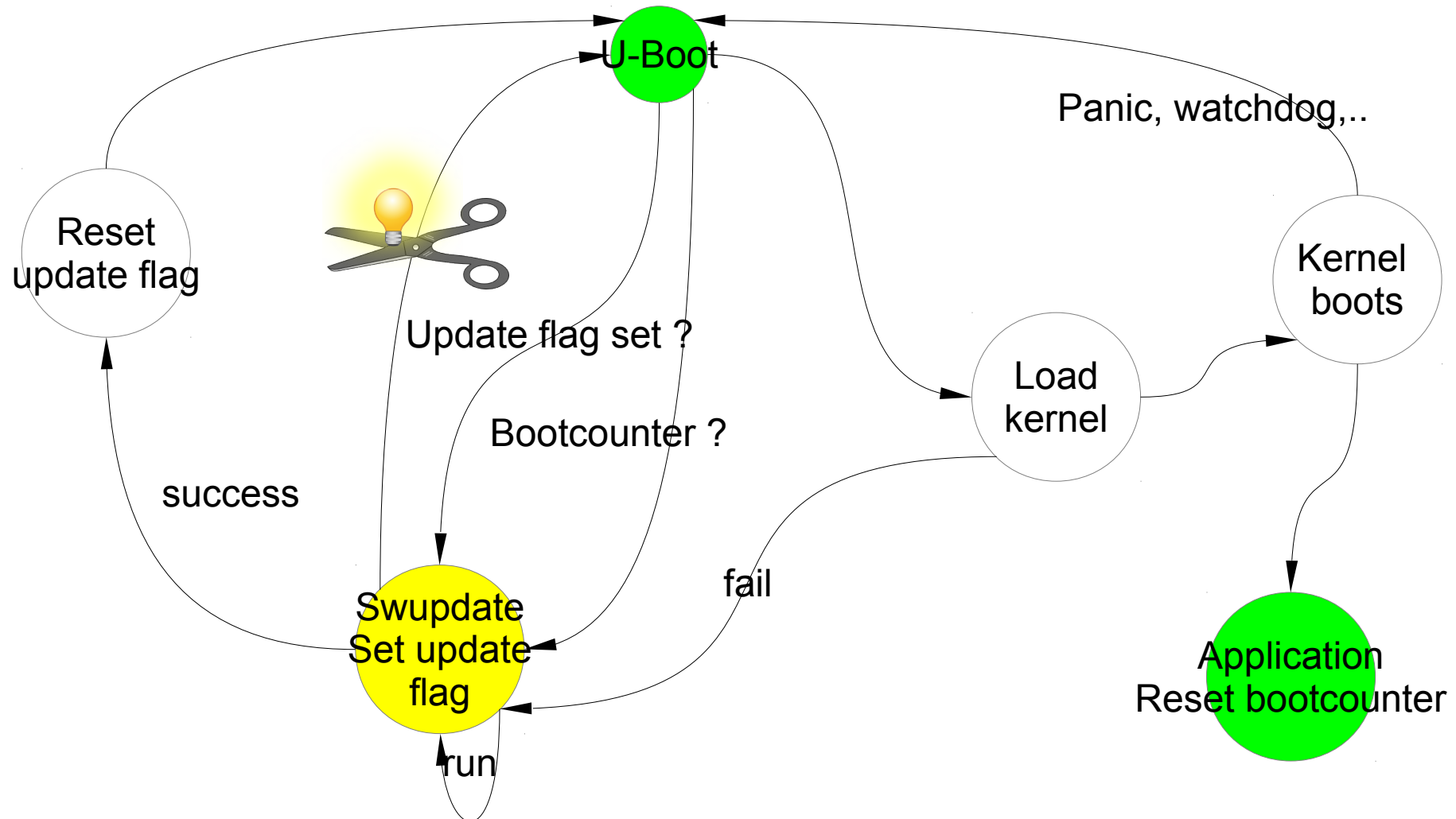
```
images: (  
  {  
    filename = "core-image-base-myboard.ubifs";  
    volume = "rootfs";  
  },  
  {  
    filename = "uboot-env";  
    type = "uboot";  
  },  
  {  
    filename = "ulmage";  
    volume = "kernel";  
  },  
  {  
    filename = "fpga.bin";  
    type = "fpga";  
  }  
);
```

# sw-description: scripts, u-boot

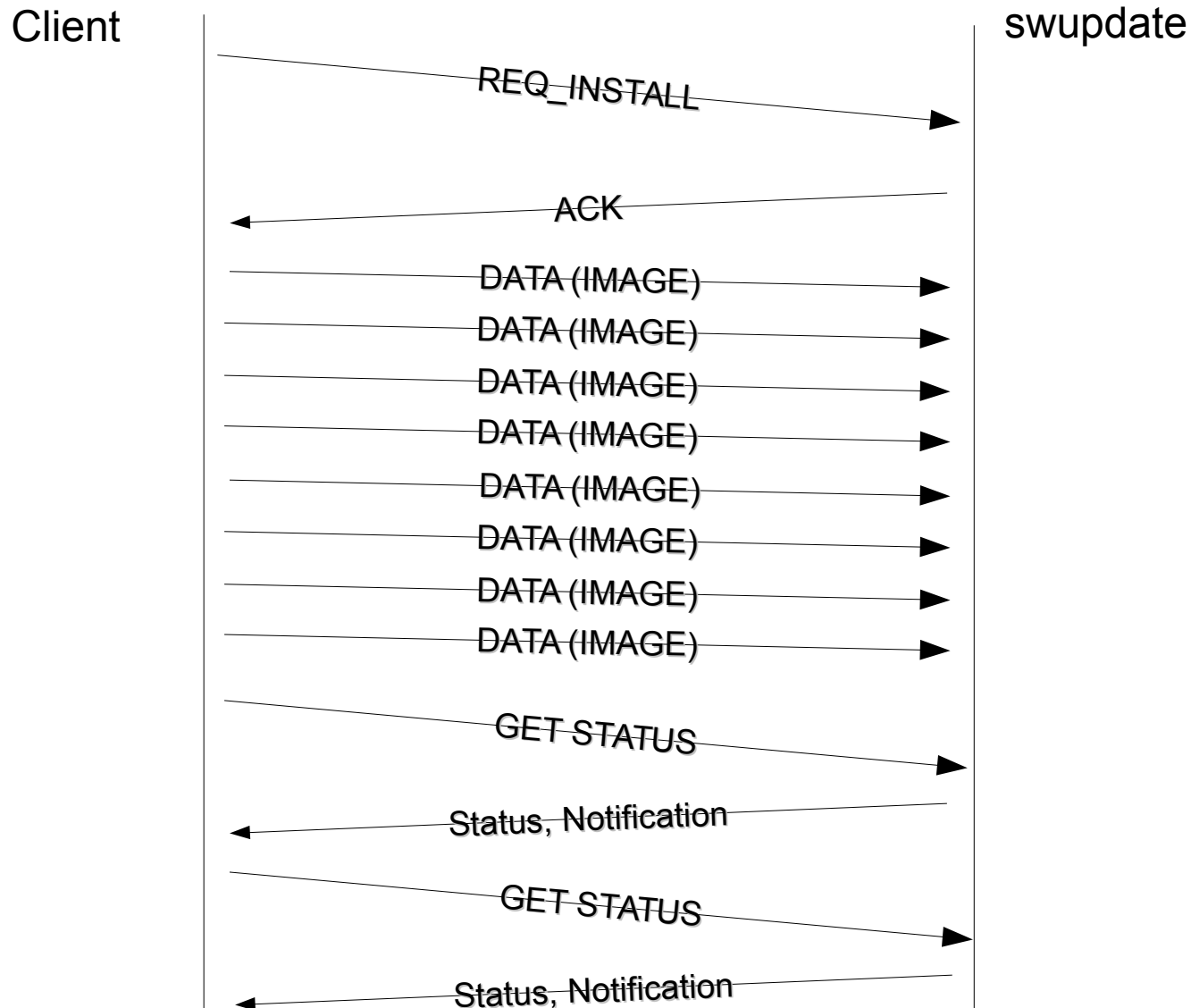


```
scripts: (  
    {  
        filename = "test.lua";  
        type = "lua";  
    },  
    {  
        filename = "sdcard.lua";  
        type = "lua";  
    },  
    {  
        filename = "test_shell.sh";  
        type = "shellscript";  
    }  
);  
  
uboot: (  
    {  
        name = "vram";  
        value = "4M";  
    }  
)
```

# Recovery from failures



# API for external client



# Updating from browser




Software Upgrade and Recovery - Mozilla Firefox

File Edit View History Bookmarks Tools Help

Software Upgrade and ...

192.168.2.212:8080

Google



## Software Update

**Software Upload**

Update Firmware :  No file selected.

Waiting for requests...

[network\_initializer] : Main thread sleep again !

SWUPDATE successful !

[update\_uboot\_env] : Updating U-boot environment

[start\_shell\_script] : Calling shell script /tmp/test\_shell.sh postinst: return with 0

[start\_lua\_script] : Script output: Post installed script called script end

[start\_lua\_script] : Calling LUA /tmp/sdcard.lua

[start\_lua\_script] : Script output: Post installed script called script end

[start\_lua\_script] : Calling LUA /tmp/test.lua

Installing image core-image-base-skyboard-evb.ubifs into volume /dev/ubi1\_1(rootfs)

[install\_images] : Found installer for stream core-image-base-skyboard-evb.ubifs ubivol

U-Boot environment updated

[install\_images] : Found installer for stream uboot-env uboot

Installing image ulmage into volume /dev/ubi0\_0(kernel)

# Using with Yocto



- Meta-swupdate
- It generates a ramdisk suitable for u-boot (.uboot.gz)
- “dora” and “daisy” branches
- Footprint RAMDISK (gzipped) : 2.6 – 7 MB
  - Typical: ~4MB

# Handler in LUA



```
require ("swupdate")

fpga_handler = function(image)
    print("Install FPGA Software ")

    for k,l in pairs(image) do
        print("image[" .. tostring(k) .. "] = " .. tostring(l) )
        swupdate.notify(swupdate.RECOVERY_STATUS.RUN,0,
            "image[" .. tostring(k) .. "] = " .. tostring(l))
    end

    return 0
end

swupdate.register_handler("fpga",fpga_handler)
```



# swupdate todo list



- Create a community around the project
- Security: add support for signed images !
- Low resources: support for full streamable image
- New handlers

# Links



- Swupdate sources at <https://github.com/sbabic/swupdate>
- Documentation at <http://sbabic.github.io/swupdate>
- Mailing list: [swupdate@googlegroups.com](mailto:swupdate@googlegroups.com)
- <http://www.denx.de/>

# Questions ...

- It's your turn now...

