

Multi-core scheduling optimizations for soft real-time applications

a cooperation aware approach

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sponsors:



ProFUSION
embedded systems

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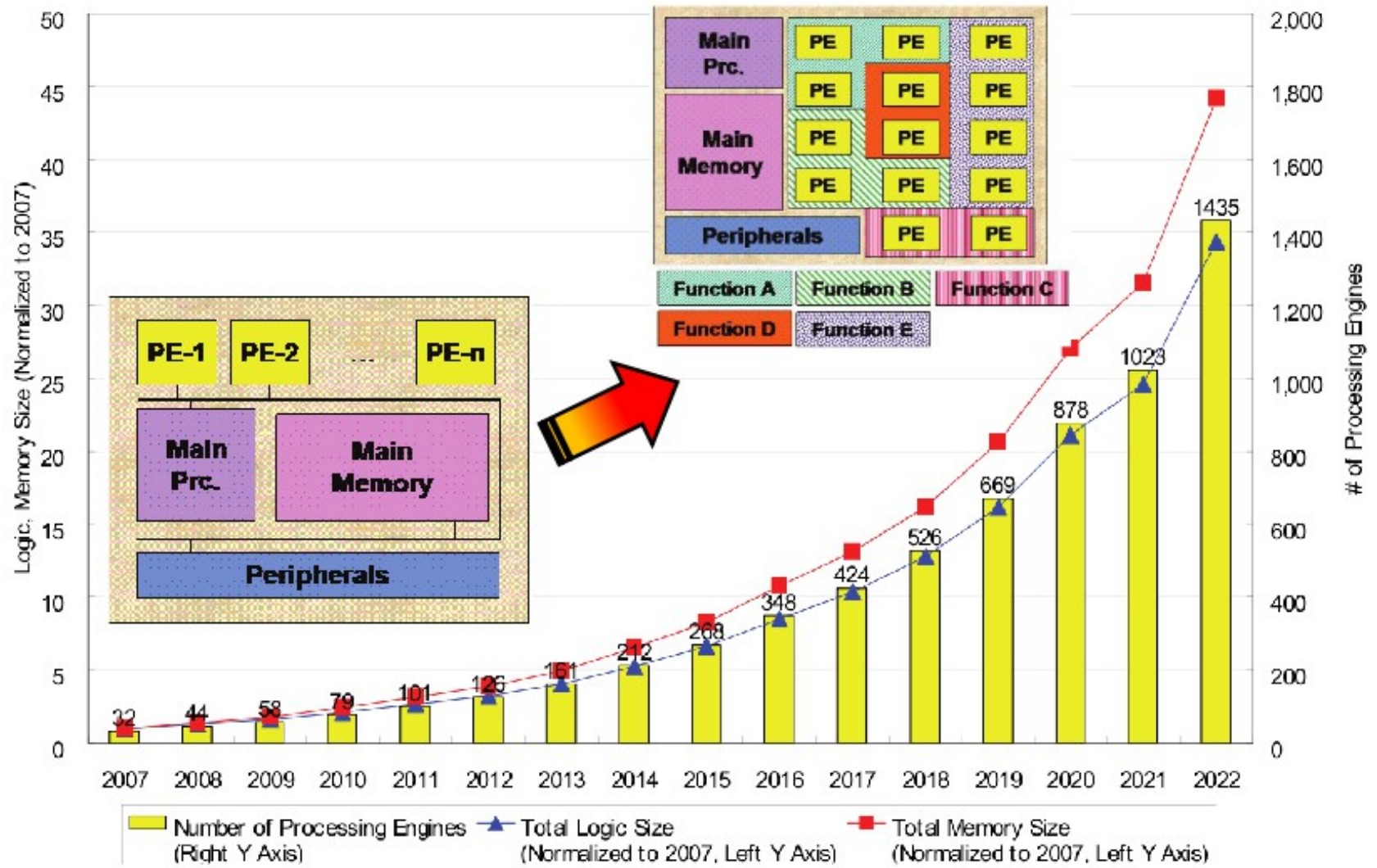
William Fornaciari

Wolfgang Betz

Agenda

- Introduction
 - Motivation
 - Objectives
 - Analysis
 - Optimization description
 - Experimental results
 - Conclusions & future works
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Introduction - motivation

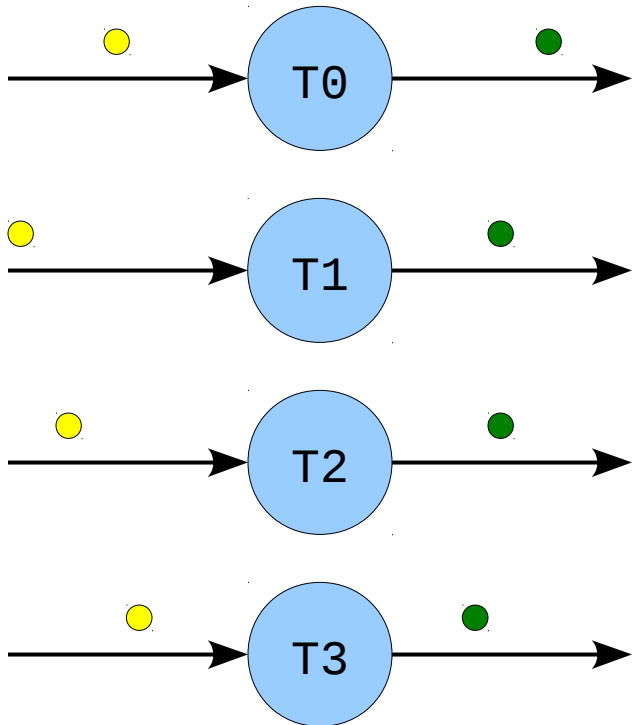


Introduction – motivation

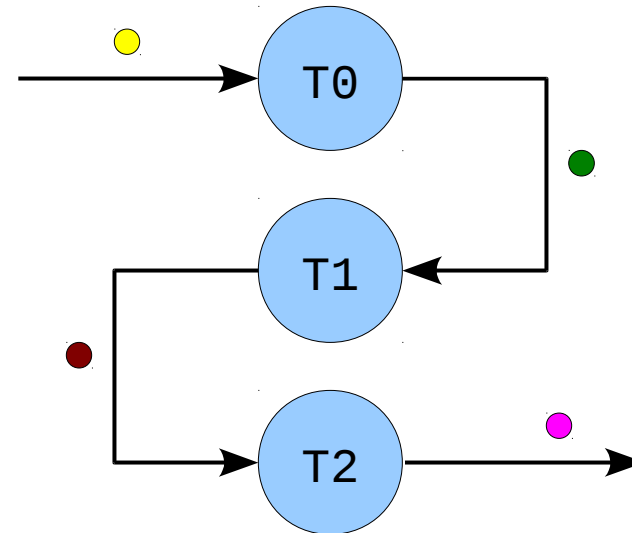
- SMP + RT
 - ♦ Multiple processing units inside a processor
 - ♦ Determinism
 - Parallel Programming Paradigms
 - ♦ Data Level Parallelism (DLP)
 - Competitive tasks
 - ♦ Task Level Parallelism (TLP)
 - Cooperative tasks
-

Introduction - motivation

- DLP



- TLP



- Characterization:
 - ◆ Synchronization
 - ◆ Communication

Introduction – motivation

- Linux RT scheduler (mainline)
 - ♦ Run as soon as possible (based on prio)
 - ↔ Use as many CPUs as possible
 - ♦ Ok for DLP!

But, what about TLP?

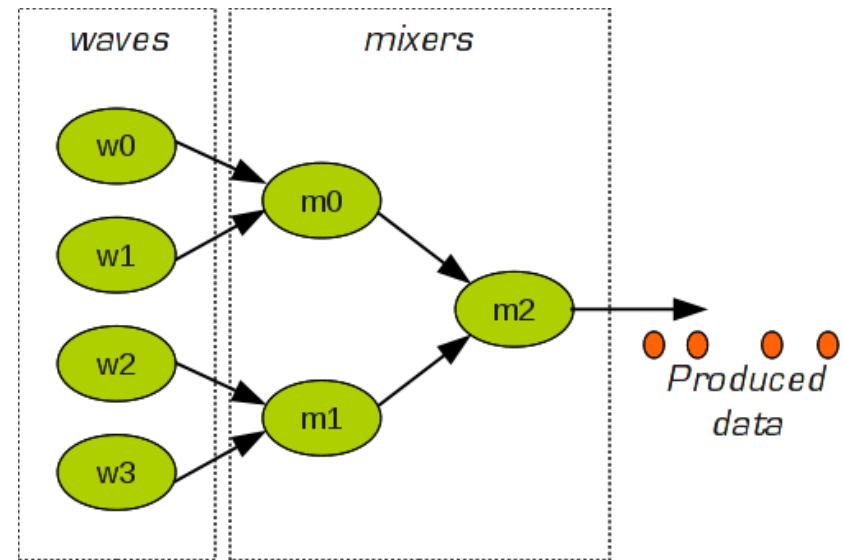
Anyway, why do we care about TLP?

Objectives

- Study the behavior of RT Linux scheduler for cooperative tasks
 - Optimize the RT scheduler
 - Smooth integration into mainline kernel
 - Don't throw away everything
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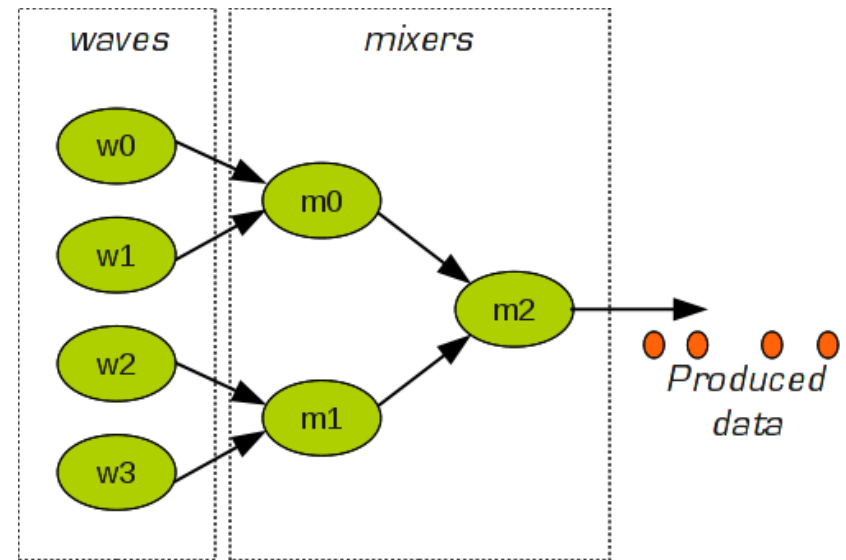
Analysis – benchmark

- Simulation of a scenario where SW replaces HW
- Multimedia-like
- Mixed workload: DLP + TLP
- Challenge: map **N** tasks to **M** cores optimally



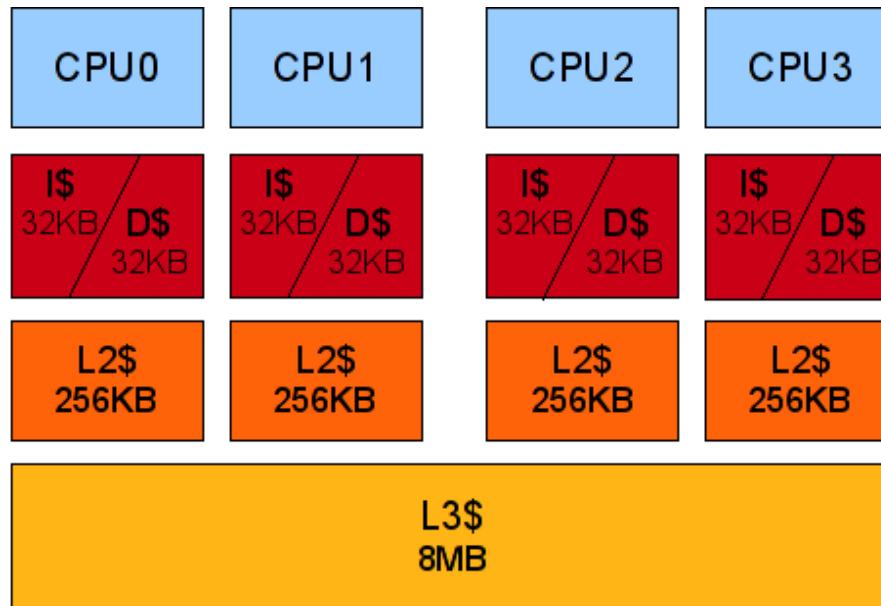
Analysis - metrics

- Throughput
 - Sample mean time
- Determinism
 - Sample variance



Analysis - metrics

- Influencing factors
 - Preemption-disabled
 - IRQ-disabled
 - **Locality of wake-up**



Intel i7 920:
4 cores
2.8 GHz

Analysis – locality of wake-up

- Migrations

- b)** occasional migrations

```
wave0: 30212133110230332330331103232001102111111120101010101
wave1: 22330301333321201012103212101233321032023033333333333
wave2: 033332232302003111201211330021322233323330220222222222
wave3: 110211120211101030031121003030120101101111111010101010
mixer0: 322210301110320231310303021213120013220320230333333333
mixer1: 001003321202220131103203212130320331201031033022010101
mixer2: 230101020201202020121020021010130101201202302010101010
monitor: 1130221333331313120321333032222232331231111112222222222
```

Analysis – locality of wake-up

- Cache-miss rate measurements

	1 CPU	2 CPUs	4 CPUs	Increase (1 - 4)
Load	7.58%	8.99%	9.44%	+24.5%
Store	9.29%	9.78%	11.62%	+25.1%

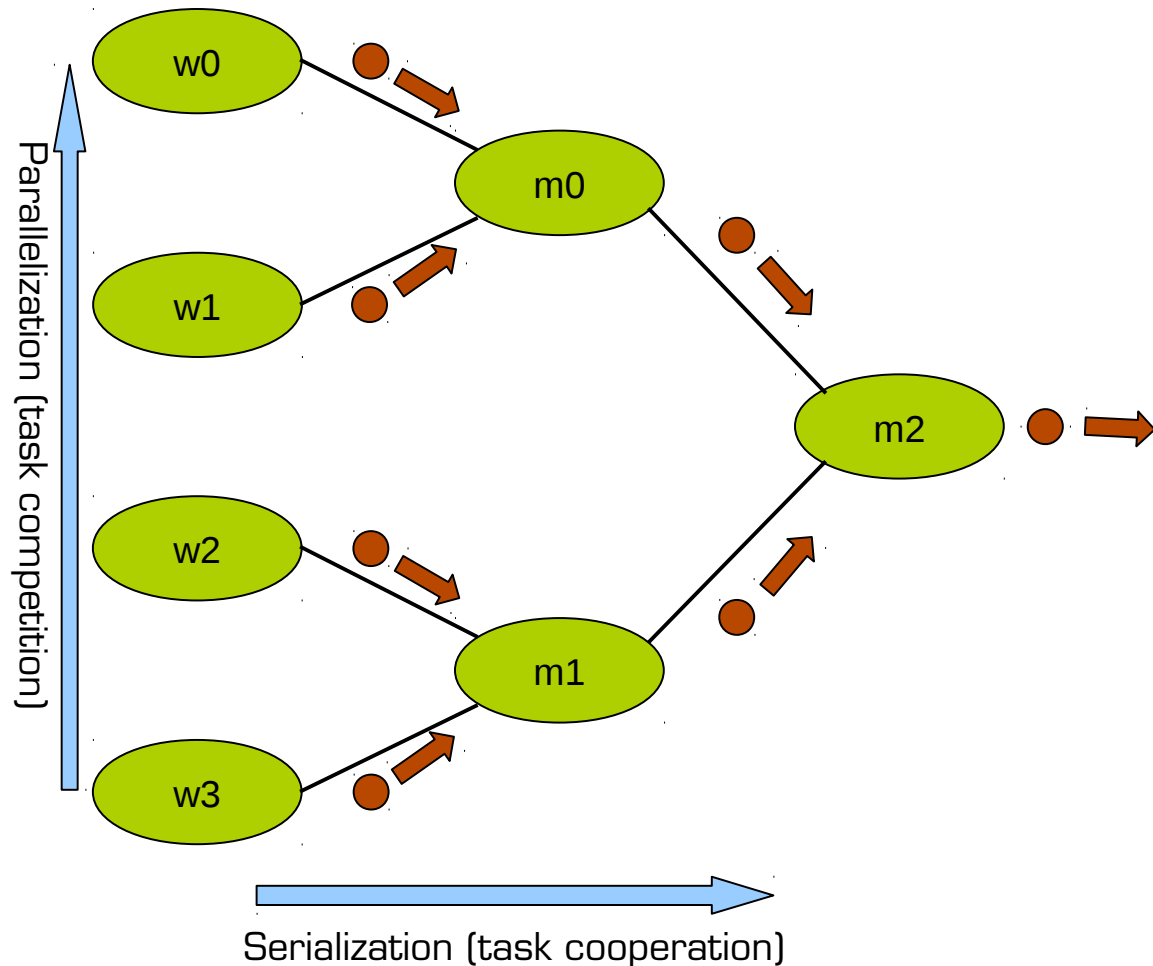
Analysis – conclusion

- Why do we care about TLP?
 - Common parallelization technique
 - What about TLP?
 - Current state of Linux scheduler is not as good as we want
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Solution – benchmark

- **Abstraction:**

One application level
sends data to another



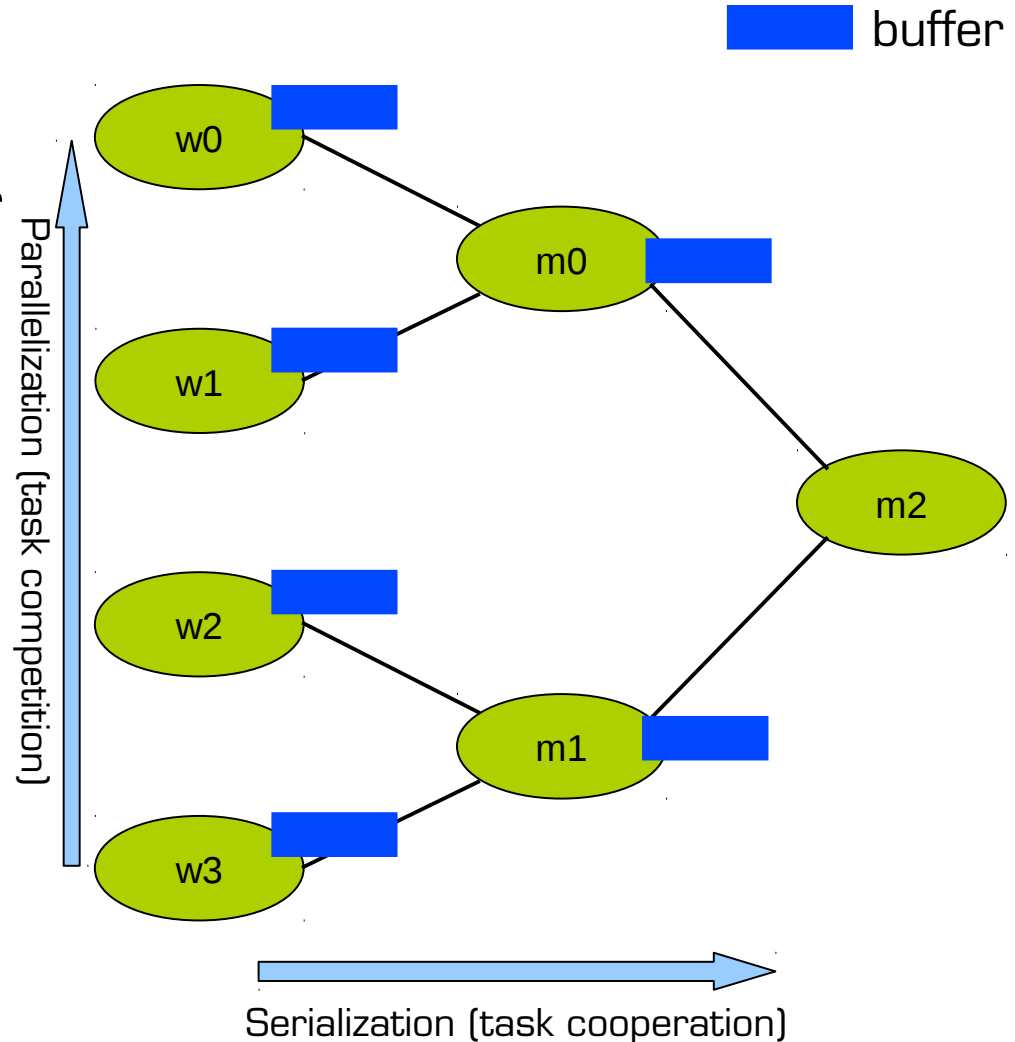
Solution - benchmark

- **Abstraction:**

One application level
sends data to another

- **Reality:**

shared buffers +
synchronization



Solution – benchmark

- **Abstraction:**

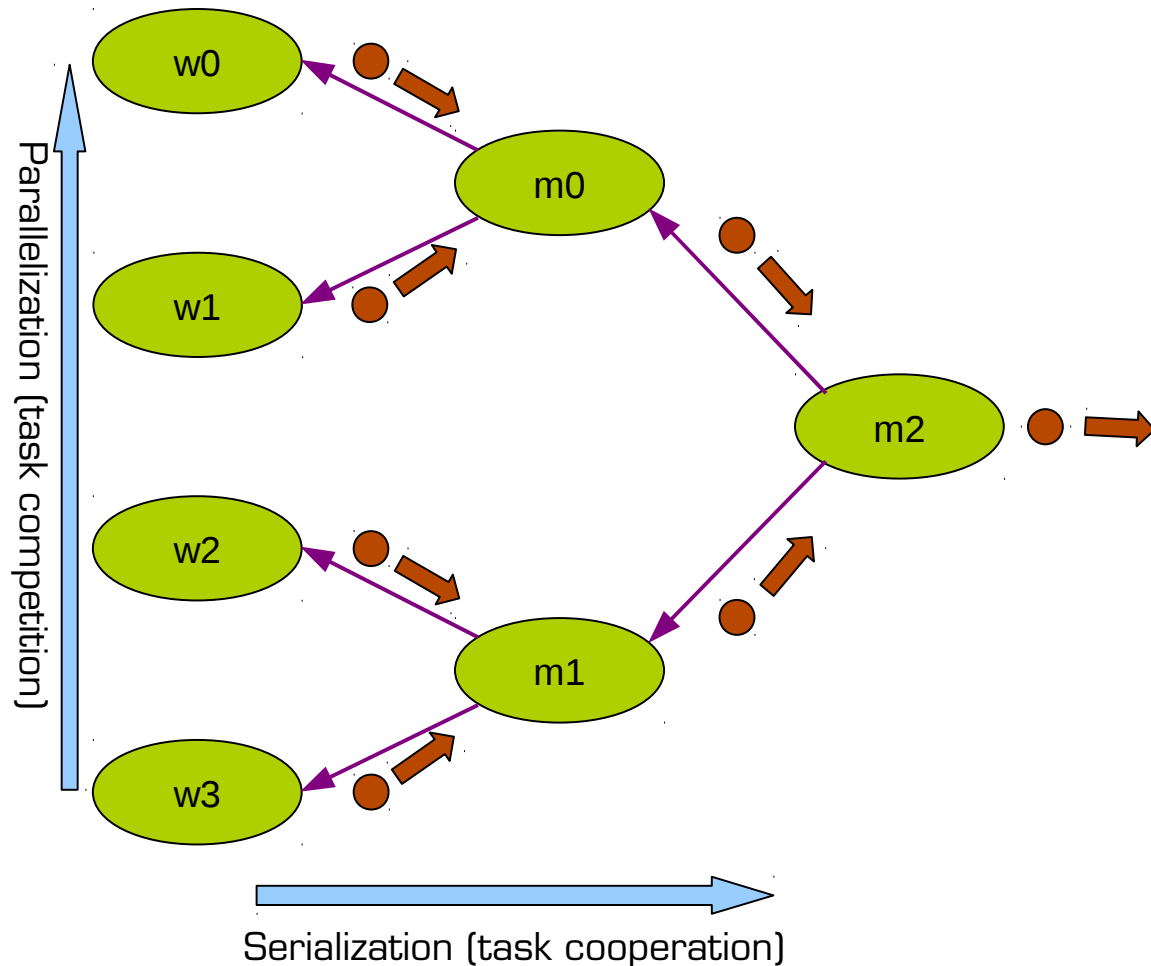
One application level
sends data to another

- **Reality:**

shared buffers +
synchronization

- **Dependencies:**

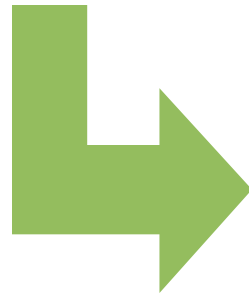
Define dependencies
among tasks in the
opposite way of
data flow



Solution – idea

Dependency followers

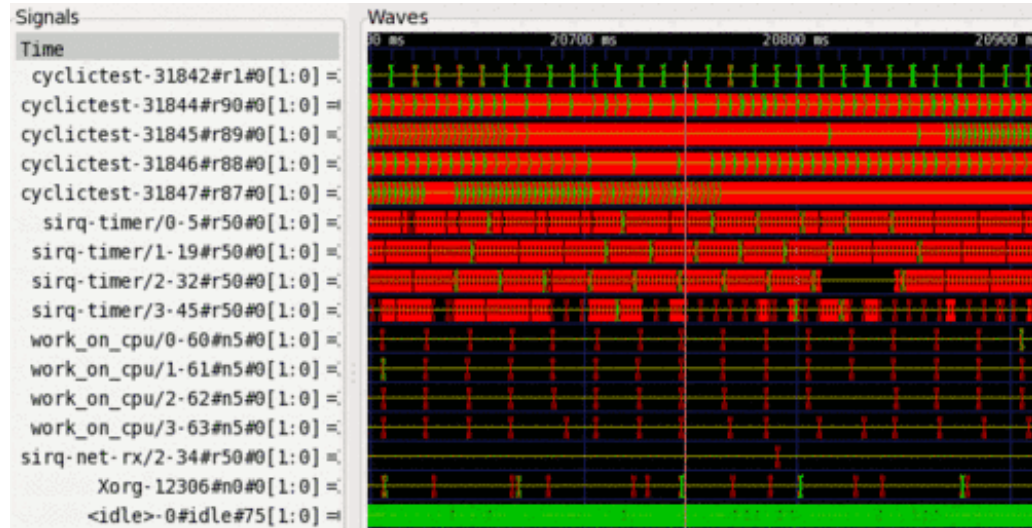
**If data do not go to tasks,
then the tasks go to where data were produced**



Make tasks run on
same CPU of their
dependencies

Measurement tools

- Ftrace
- sched_switch tool (Carsten Emde)*
- gtkwave
- perf
- adhoc scripts



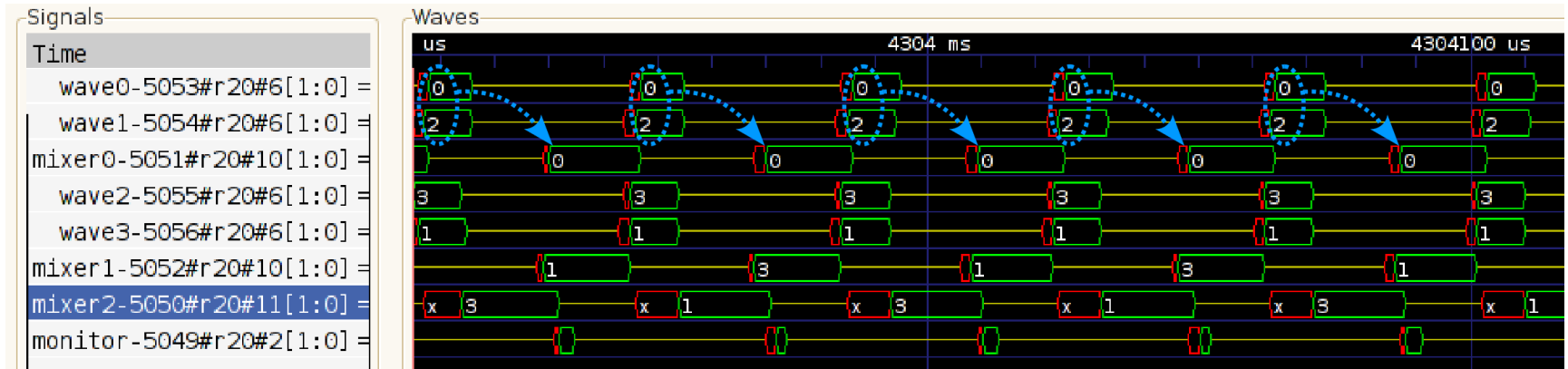
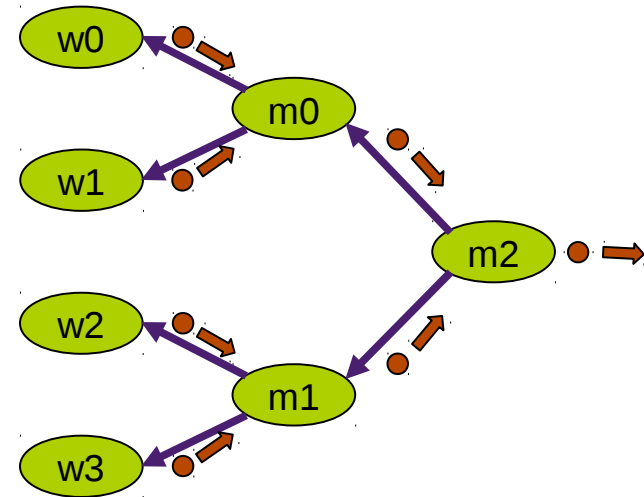
* <http://www.osadl.org/Single-View.111+M5d51b7830c8.0.html>

Solution – task-affinity

Dependency followers

Task-affinity:

selection of the CPU in which a task (e.g. m0) executes takes into consideration the CPUs in which its dependencies (e.g. w0 and w1) ran last time.



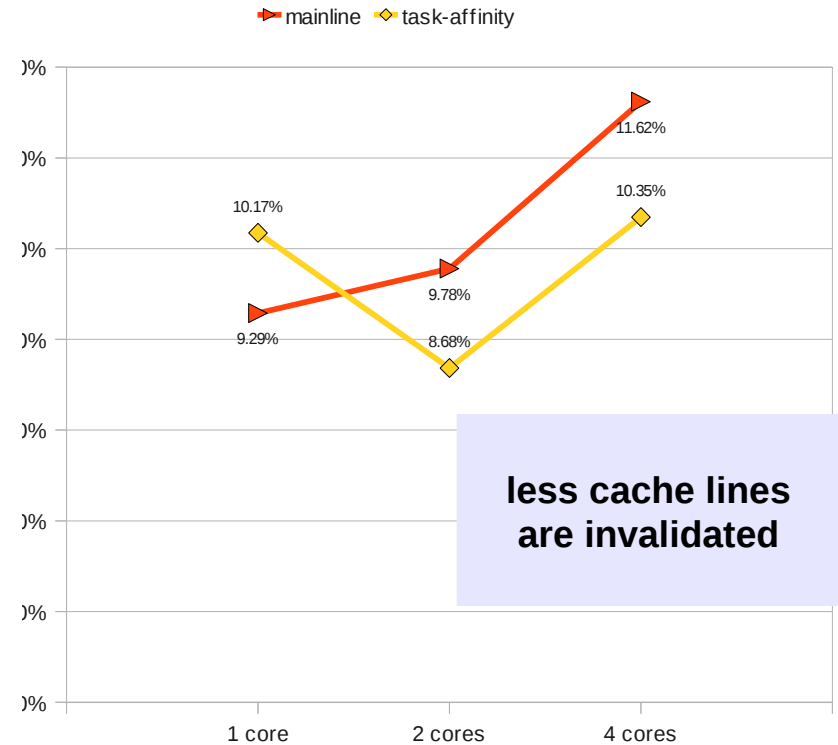
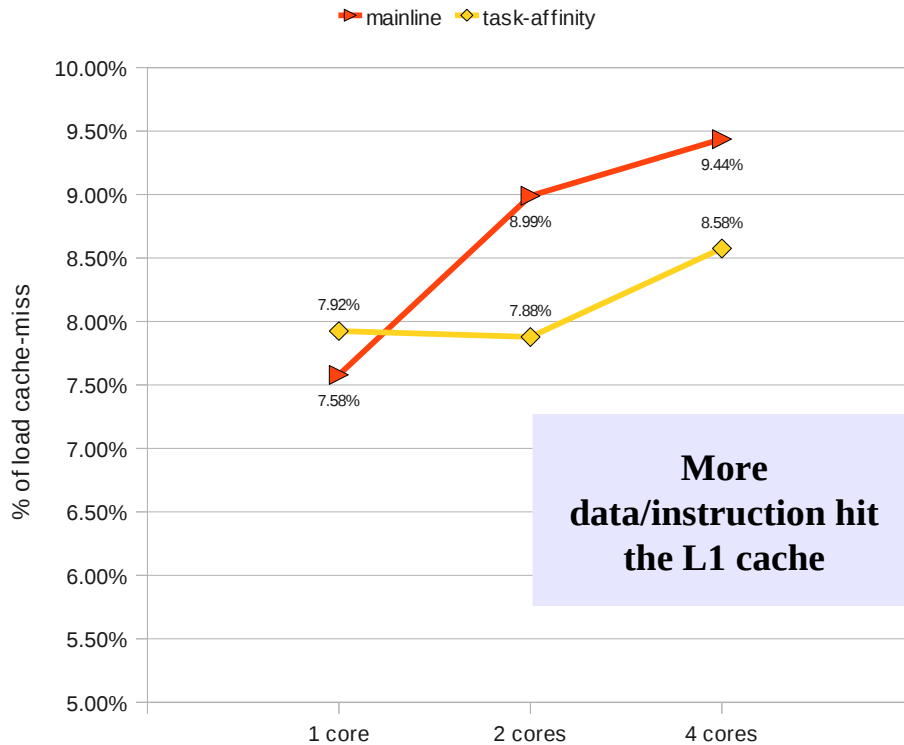
Solution – task-affinity implementation

- 2 lists inside each `task_struct`:
 - `taskaffinity_list`
 - `followme_list`
 - 2 system calls to add/delete affinities:
 - `sched_add_taskaffinity`
 - `sched_del_taskaffinity`
-

Experimental results

Cache-miss rates

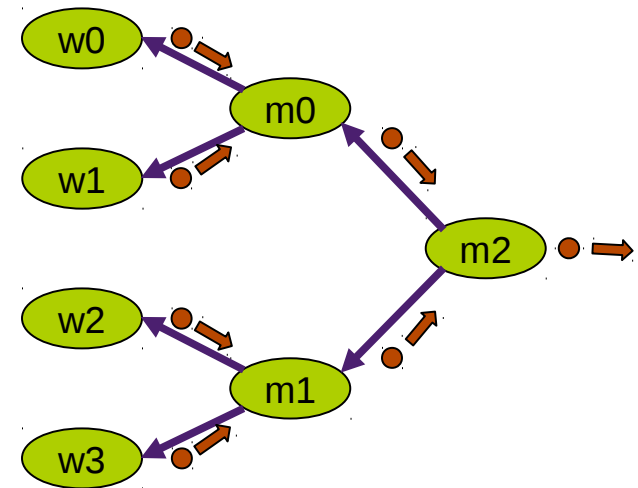
- Measurements without and with task-affinity



Experimental results

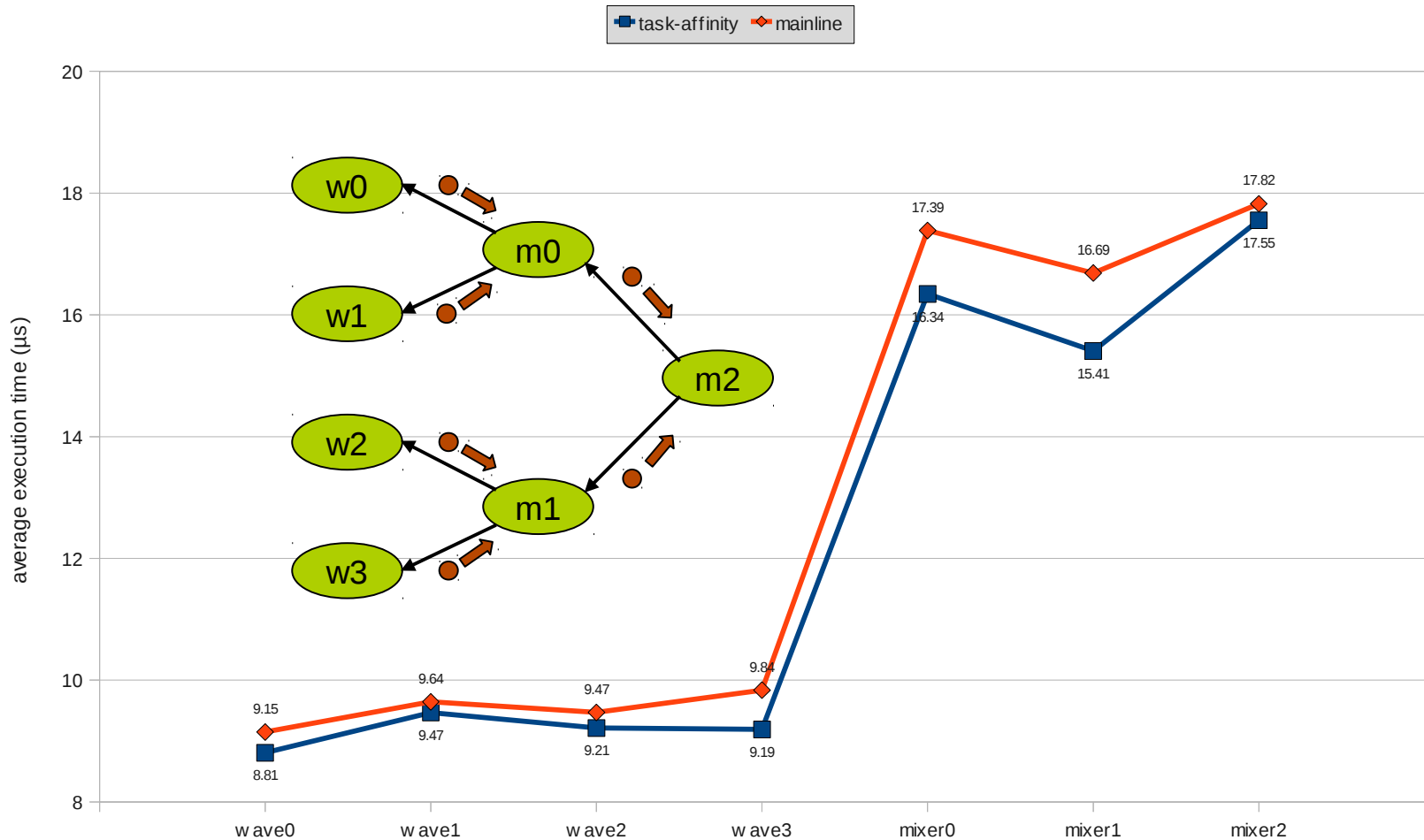
What exactly to evaluate?

- Cache-miss rate is not exactly what we want to optimize
- Optimization objectives:
 - Lower the time to produce a single sample
 - Increase determinism on production of several samples



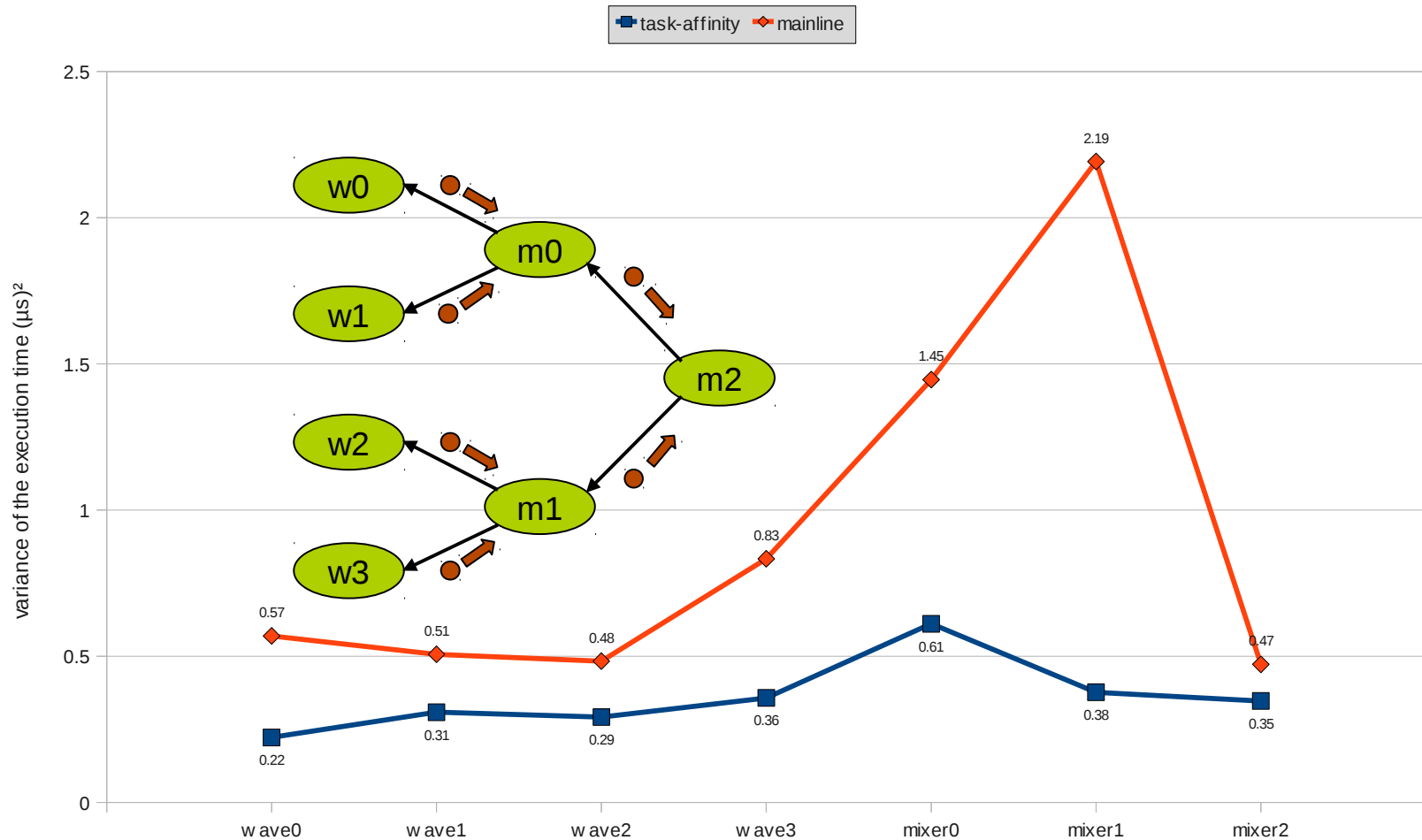
Experimental results

Average execution time of each task



Experimental results

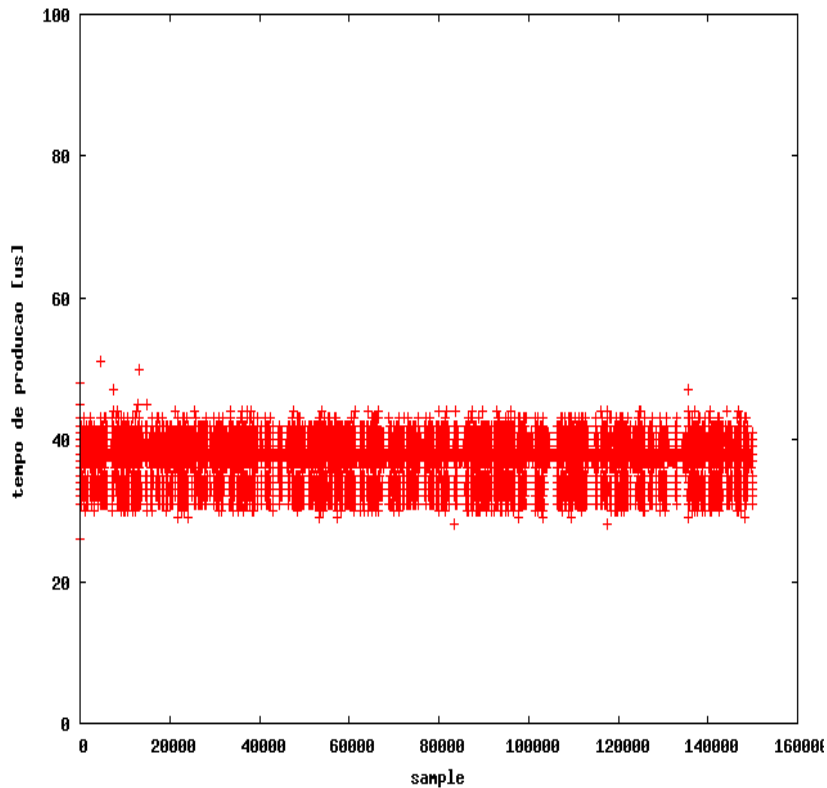
Variance of execution time of each task



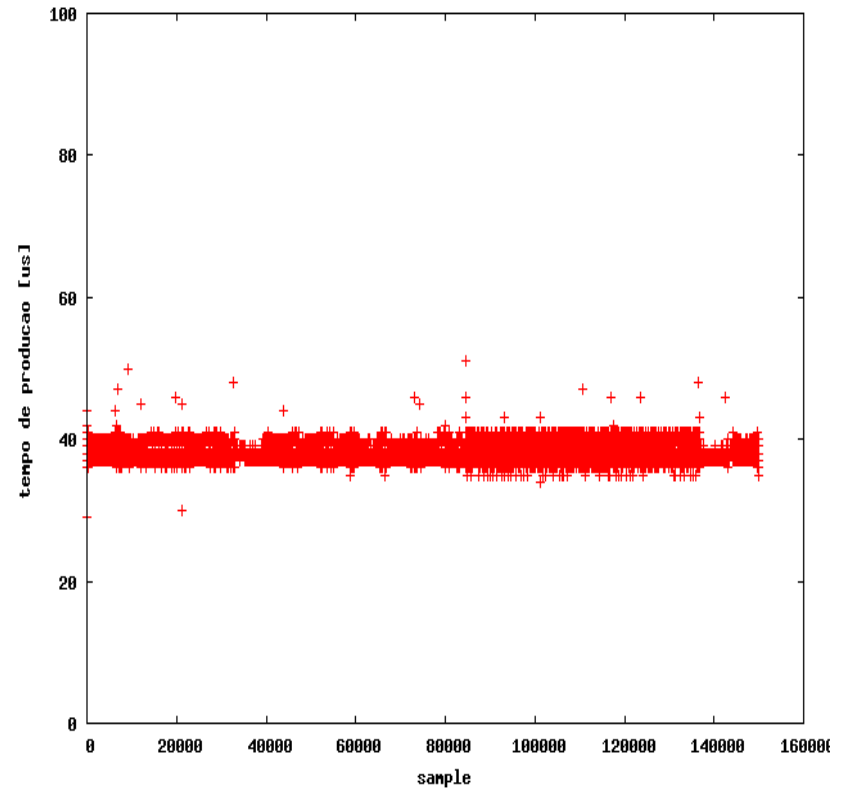
Experimental results

Production time of each single sample

- Results obtained for 150,000 samples



mainline

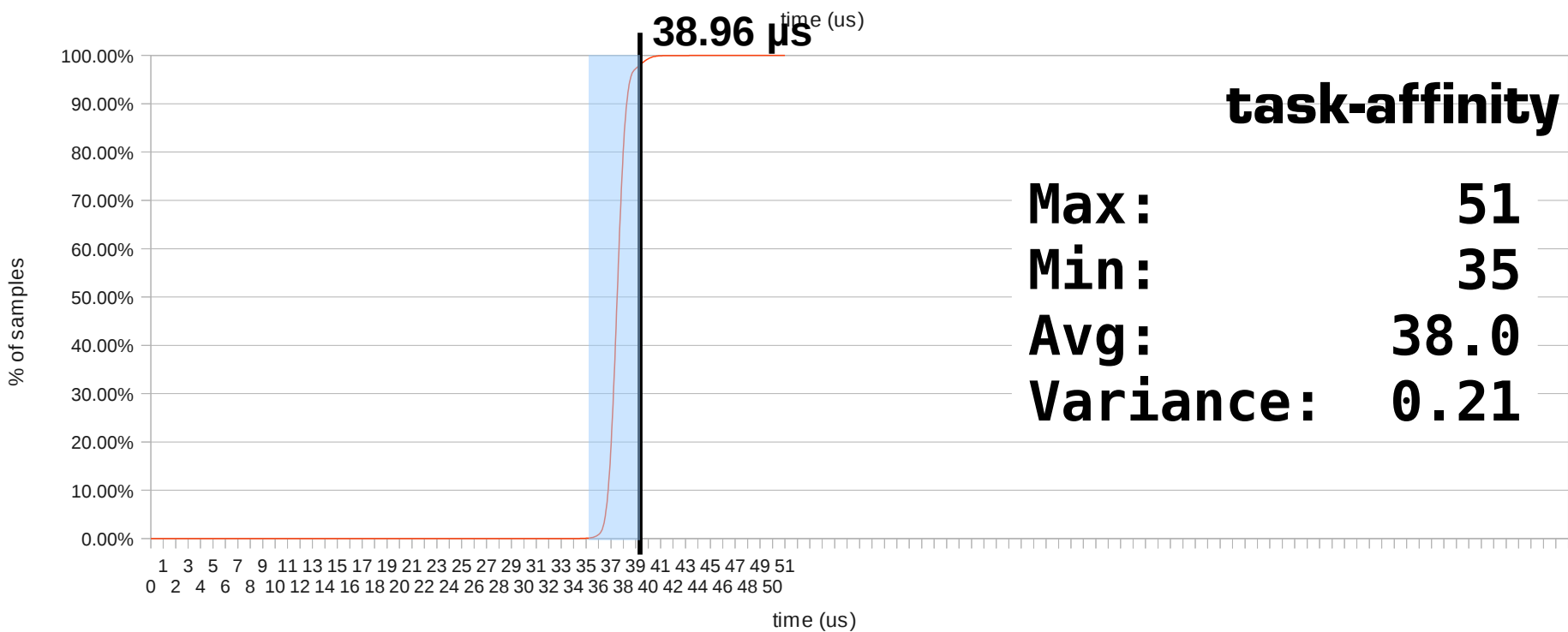
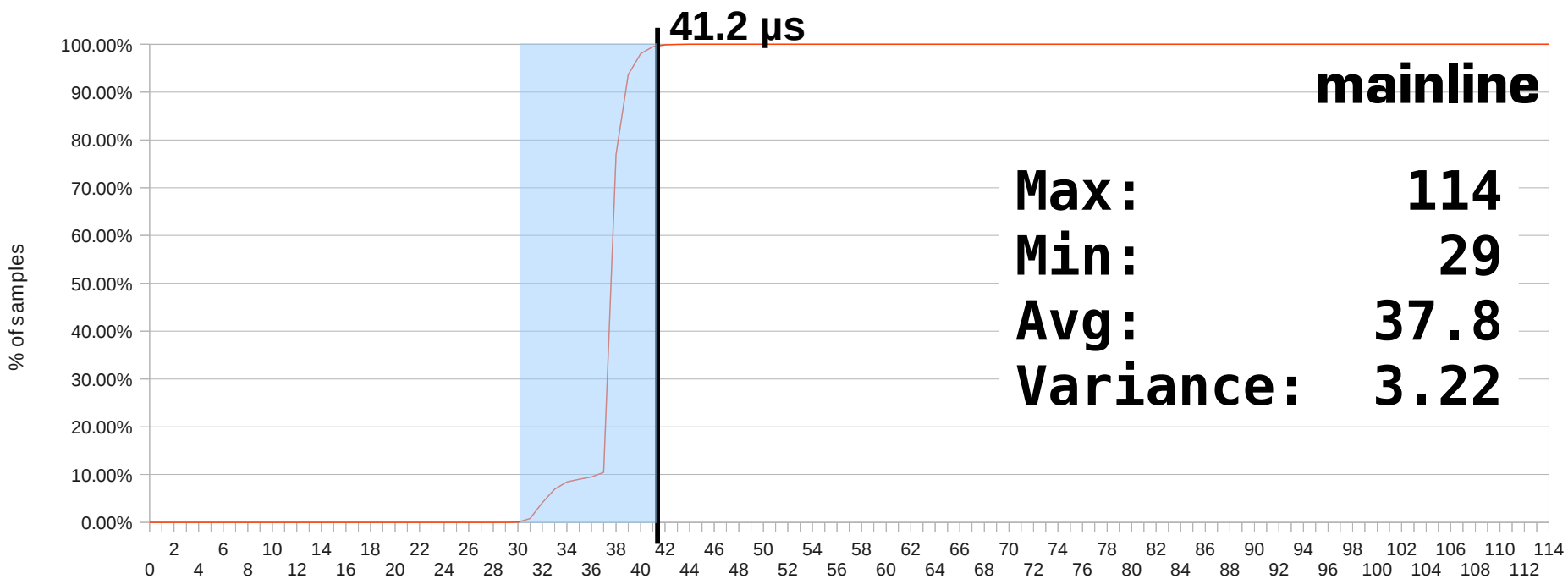


task-affinity

Experimental results

Production time of each single sample

- Empiric repartition function
 - Real-time metric (normal distribution):
 - ♦ average + 2 * standard deviation
-



Experimental results

summary

	Average	Variance	Real-time Metrics	Speedup
mainline	37.826	3.225	41.42	-
taskaffinity	38.038	0.214	38.96	5.94%

~15x

Conclusion & future works

- Average execution time is almost the same
 - Determinism for real-time applications is improved
 - Future works:
 - Better focus on temporal locality
 - Improve task-affinity configuration
 - Test on other architectures
 - Clean up the repository
-

Conclusion & future works

- Still a Work In Progress
 - Git repository:
 - ♦ `git://git.politreco.com/linux-lcs.git`
 - Contact:
 - ♦ `lucas.demarchi@profusion.mobi`
 - ♦ `lucas.de.marchi@gmail.com`
-

Q & A

Solution – Linux scheduler

Dependency followers

- **Linux scheduler:** Change the decision process of the CPU in which a task executes when it is woken up

