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Spreading the disease: Linux on microcontrollers

This presentation

- ❖ **Linux on an MCU**
- ❖ **Task**
- ❖ **Solution**



Modern MCUs

- ❖ AVR or Cortex-M
- ❖ tight integration
- ❖ limited RAM and flash
- ❖ low or ultra-low power consumption
- ❖ easy to design hardware

Example usage

- ❖ Home automation
- ❖ Industrial automation
- ❖ low-power wireless accessories

OS choice: RTOS or... Linux?

- ❖ RTOS

- ❖ mostly non-free
- ❖ often POSIX-incompliant
- ❖ may require expensive development tools

- ❖ Linux

- ❖ free and open-source
- ❖ well-developed applications
- ❖ stable and portable
- ❖ free tools (compiler, IDE, debugger)

Linux on an MCU: obstacles

- ❖ **Storage requirements**
- ❖ Performance considerations

Linux storage requirements

- ❖ Requirements are vague and architecture-dependent
- ❖ Plain case storage estimations
 - ❖ RAM: 8+ MB (+something for userspace)
 - ❖ Persistent: 2+ MB (+some for filesystem)
- ❖ Estimations for XIP
 - ❖ RAM: 1+ MB (+something for userspace)
 - ❖ Persistent: 4+ MB (+some for filesystem)
- ❖ XIP is supported only on some platforms
 - ❖ ARM is one of these

Linux on an MCU: obstacles

- ❖ Storage requirements
- ❖ **Performance considerations**

Linux performance considerations

- ❖ NB: CPU frequencies are lower than 200 MHz
- ❖ Boot-up time
 - ❖ 3+ seconds
- ❖ Latencies
 - ❖ generally higher than for an RTOS
- ❖ Overhead
 - ❖ generally bigger than for an RTOS

Linux on an MCU: so...?

- ❖ Vanilla Linux kernel will not run on a basic MCU
- ❖ Something needs tweaking
 - ❖ add external RAM/flash to the design?
 - ❖ optimize Linux kernel/userspace to run tight?
- ❖ Is it worth it?

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Home automation device

- ❖ Requirements
 - ❖ Ultra low power
 - ❖ PoE capable
 - ❖ Monitors BLE (Bluetooth Low Energy) sensors
 - ❖ [Secure] updates using USB stick or uSD

HW design considerations

- ❖ no DRAM
- ❖ MCU rather than CPU
 - ❖ ARM Cortex-M4 is a good match
 - ❖ included Ethernet support is preferable
- ❖ standalone BLE chip

MCU considerations

- ❖ ARM Cortex-M4 based solutions
 - ❖ Freescale Kinetis
 - ❖ up to 128 KB RAM
 - ❖ up to 2MB flash
 - ❖ STMicro STM32F4XX
 - ❖ up to 256 KB RAM
 - ❖ up to 2MB flash

Software considerations

- ❖ OS should be POSIX compliant
- ❖ Tools should be FOSS

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Proposed hardware design

- ❖ Considerations

- ❖ ARM Cortex-M4

- ❖ only SRAM, no DRAM

- ❖ only NOR flash (possibly uSD / eMMC)

- ❖ Selection

- ❖ STMicro STM32F29 (more SRAM than on others)

- ❖ 256 KB SRAM

- ❖ 2 MB NOR flash

ARM Linux evaluation

- ❖ Vanilla Linux kernel is too large
 - ❖ both in terms of RAM and flash usage
 - ❖ Search for projects that optimize kernel for size
- ❖ XIP kernel is a must
 - ❖ RAM is no more than 256K
 - ❖ but the flash image size is bigger

Linux for Cortex-M 1.12.0

- ❖ 2.6.33 based
- ❖ supports Cortex-M0, M3, M4
- ❖ supports Thumb mode
- ❖ recommended by Emcraft

Linux kernel

- ❖ All unnecessary stuff removed
- ❖ Thumb mode on
- ❖ vmlinux: 1042816 bytes
 - ❖ vmlinux.text: 878460 bytes
 - ❖ vmlinux.data: 61440 bytes
 - ❖ vmlinux.bss: 48624 bytes

Linux root filesystem

- ❖ Root filesystem: XIP / squashfs
 - ❖ executables come uncompressed
- ❖ Size: 851968 bytes
- ❖ We need 64+kb for RW filesystem (JFFS2)
 - ❖ further optimization needed

Linux kernel optimizations

- ❖ Compress `.data`
 - ❖ compressed size: 8220 bytes
- ❖ remove `.bss`
 - ❖ just need to zero the RAM area

Resulting flash map

- ❖ Bootloader: 0x10000 bytes
- ❖ XIP Kernel: 0xE0000 bytes
- ❖ Root filesystem (RO): 0xD0000 bytes
- ❖ Config filesystem (RW): 0x30000 bytes
- ❖ ...and we even have 64k left :)

Thanks!

❖ Questions?

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